RESIDUAL DISPLACEMENT PREDICTION OF R/C BUILDING STRUCTURES USING EARTHQUAKE RESPONSE SPECTRA

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ABSTRACT

Strong earthquake motions exceeding the current design standard level have been recorded during recent severe earthquakes in Japan. Collapsed reinforced concrete building structures are very few because the Japanese building code requires high performance for their seismic safety. Some of them, however, show moderate or severe damage, and the total cost for their repair often exceeds that of reconstruction. It is, therefore, important that the building design code ensure not only its seismic safety, but also its reparability performance. The residual displacement after earthquakes is one of the most important factors for predicting their reparability performance. In previous studies, most of researchers estimate the residual displacement of buildings based on non-linear earthquake response analyses.

In this paper, a simplified method is proposed to predict the residual displacement where it is approximated by the point where the line connecting two displacement peaks in positive and negative domains of load-deflection curves crosses the abscissa. Considerable prediction errors are found between predicted displacements in the proposed method and those directly obtained after non-linear response analyses. The accuracy of predicted residual displacement is, however, much improved when the 3rd displacement peak is taken into account in addition to the 1st and 2nd displacement peaks. The proposed method is further extended and applied to the conventional capacity spectrum method to predict peak displacements. It is revealed that the method can successfully predict the residual displacements and enhance the conventional capacity spectrum method.

1. INTRODUCTION

Most buildings, which satisfied the current design criteria, survived recent severe earthquakes in Japan, owing to the high requirement of the seismic performance to prevent building collapse and human casualties. Some building structures, however, showed damage to some extent after earthquakes and it cost much more than expected by building owners to have them repaired. They are concerned with not only direct but also indirect losses such as business downtime. Performance-based design therefore should include reparability and functionality of buildings after earthquakes.

To identify the reparability performance, an effective evaluation index is required. In recent studies especially for the precast concrete members, the residual displacement control is considered an effective method to assure the reparability performance. In this paper, the residual displacement after excitations is employed as an index to identify reparability performance of reinforced concrete structures. A simplified method is proposed to predict the residual displacement after excitations, and its accuracy is discussed through comparison with results of non-linear response analyses.

2. PREDICTION OF RESIDUAL DISPLACEMENT WITH PEAK RESPONSE DISPLACEMENTS

2.1 Definition of estimator *R* of residual displacement

Reinforced concrete structures are idealized with an SDOF system in this study as shown in Figure 1. Goto et al. (1970) estimate the residual displacement δ_r after excitations (point A) with the mean value of maximum response displacements in the positive and negative directions. Kitamura et al. (2009) concludes that the response after the maximum displacement particularly influences the residual displacement δ_r . In this study, the estimator *R* of residual displacement δ_r is defined for better predictions under rational assumptions in the following manner.

The 1st peak P_1 in a non-linear earthquake response analysis is defined as the maximum response point, which is supposed to be found in the positive domain hereafter, as shown in Figure 1. The 2nd peak P_2 is defined as the maximum response point in the opposite negative domain after P_1 , and the 3rd peak P_3 is then defined as the 2nd maximum response point in the opposite positive domain after P_2 . As shown below, subsequent peaks P are then defined in the analogous manner described above (Figure 2).

• P_{2i-1} : *i*-th max in the positive domain. • P_{2i} : *i*-th max in the negative domain.

The estimator R_N of residual displacement δ_r is then defined as the point

where a line connecting P_N and P_{N+1} crosses the abscissa as shown in Figure 1.

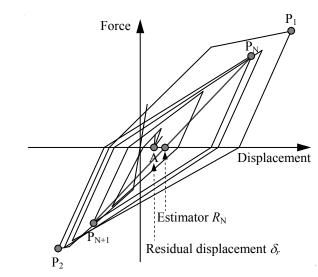


Figure 1: Definition of estimator R of residual displacement

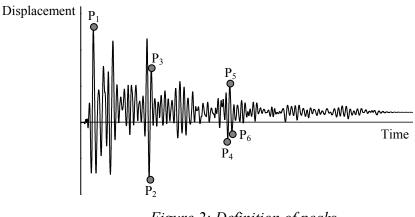
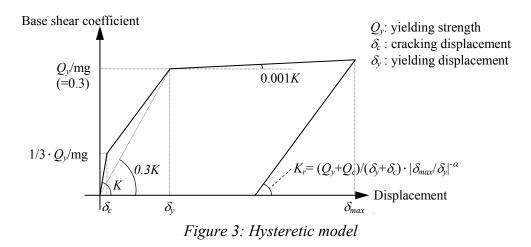


Figure 2: Definition of peaks

2.2 Modeling of building structure

The hysteretic rules for building structures are idealized with Takeda model (Takeda et al., 1970) in the nonlinear earthquake response analyses (Figure 3). The base shear coefficient and the natural period of the structures are 0.3 and 0.3(s), respectively, in all analyses. A viscous damping factor proportional to instantaneous stiffness is assumed to be 5% of the critical damping. The cracking strength is assumed 1/3 of yielding strength and the secant stiffness at yielding is assumed 30% of the elastic stiffness. The post-yielding stiffness is assumed 0.1% of the elastic stiffness. The hysteretic parameter α for unloading stiffness in Takeda model is 0.5. Three observed earthquake records are applied for excitation, which are El Centro NS 1940, Tohoku NS 1978, and JMA Kobe NS 1995. The accelerations are scaled so that the maximum ductility factor μ of the model should reach 1.0, 2.0 and 3.0, respectively. Note that the residual response, rather than the structural safety during large inelastic response, is the primary concern in this study, and the maximum ductility factor μ is therefore limited to 3.0 herein.



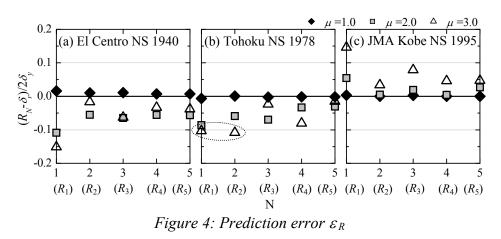
2.3 Results of analyses

Nine cases consisting of 3 parameters for input earthquake records and 3 target maximum ductility factors are investigated in this study, and the prediction error ε_R of estimator R_N defined in Equation (1) is examined in each case:

$$\varepsilon_{R} = (R_{N} - \delta_{r})/2\delta_{v} \tag{1}$$

where, R_N is the N-th estimator of δ_r (N=1, 2, 3,...), δ_r is the residual displacement after non-linear response analysis, and δ_y is the yielding displacement of the model structure.

Figure 4 shows prediction errors ε_R with respect to N. In case of μ =1.0, the error ε_R is negligibly small regardless of the value of N in any earthquake since the values of R_N and δ_r are much smaller than δ_y . In cases of μ =2.0 and 3.0, the error is much larger and does not necessarily decrease with increase in the value of N. The results found in Figure 4 can be explained as fallows.



Supposing the 1st peak P_1 falls within the positive domain and bearing the definition of estimator R_N described in section 2.1 in mind, the values of

 R_1 to R_5 satisfy the following relation: $R_2 < R_1$, $R_2 < R_3$, $R_4 < R_3$, $R_4 < R_5$ (cf. Figure 5). When δ_r is smaller than R_2 (Figure 5 left), R_2 (N=2) is always a better estimator of δ_r than R_1 (N=1) due to the relation of $\delta_r < R_2 < R_1$. Thus the prediction is improved with increase in N. On the other hand, when δ_r is larger than R_1 , R_1 (N=1) is a better estimator than R_2 (N=2) due to the relation of $R_2 < R_1 < \delta_r$. Thus the prediction is not improved with increase in N. The estimator R_N with larger value of N does not necessarily give a better estimator of δ_r under the values of N equal to around 5 or 6 as investigated in this study, and the accuracy depends on the relation between R_{N-1} , R_N and δ_r .

Figure 6 shows the ratio $\rho = |(R_2 - \delta_r)/(R_1 - \delta_r)|$ to identify a better estimator, where R_2 is a better estimator when $\rho < 1.0$ and R_1 is a better estimator when $\rho \ge 1.0$. As can be found in the figure, a plot in case of Tohoku NS 1978 (μ =3) can be better predicted by R_1 , and this is consistent with the result found in Figure 4 as enclosed by a dotted line where the prediction error of R_2 is larger than that of R_1 .

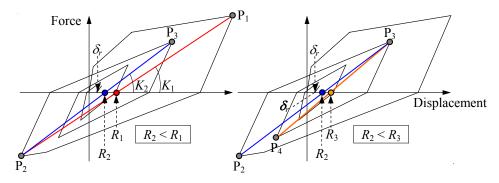


Figure 5: Relationship of R_1 , R_2 , R_3 , and δ_r

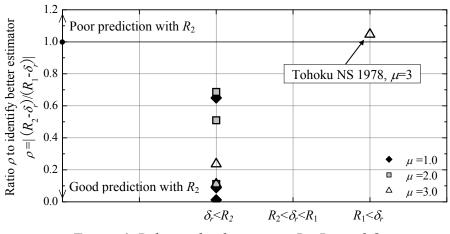


Figure 6: Relationship between ρ , R_1 , R_2 , and δ_r

2.4 Determination of estimator R

The simplest procedure to predict the residual displacement δ_r is to employ R_1 discussed above. There are, however, some cases where R_2 is a better estimator than R_1 as shown in Figures 4 and 6. To identify a better estimator between R_1 and R_2 , the following procedure is discussed herein. The difference between R_1 and R_2 is first examined. As can be found in Figure 6, the following tendency can be derived.

(1)When δ_r is larger than R_1 , the ratio ρ is close to 1.0 and the difference between R_1 and R_2 is therefore small.

(2)When δ_r is smaller than R_1 , the ratio ρ is generally much smaller than 1.0 and the difference between R_1 and R_2 is large.

To describe the closeness of R_1 and R_2 discussed above, an equivalent stiffness ratio K_1/K_2 is employed, where K_N signifies the equivalent stiffness connecting peak values P_N and P_{N+1} as shown in Figure 5. Additionally, a new parameter γ defined in Equation (2) is considered to express which of R_1 and R_2 is closer to δ_r . When δ_r is located just on the center of R_1 and R_2 , γ is equal to 0.

$$\gamma = \left\{ \delta_r - \frac{\left(R_1 + R_2\right)}{2} \right\} / 2\delta_y \tag{2}$$

Figure 7 shows the relationship between γ and K_1/K_2 . When K_1/K_2 is smaller than 1.0, γ tends to be negative, which means δ_r is closer to R_2 . On the other hand, when K_1/K_2 is close to 1.0, γ tends to distribute around 0 or in the positive domain, and δ_r is therefore closer to R_1 .

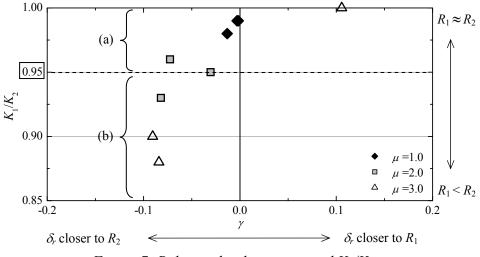


Figure 7: Relationship between γ and K_1/K_2

As stated earlier, R_1 can be the simplest estimator of δ_r . As can be found in Figure 7, however, R_2 can be a better estimator of δ_r in case of K_1/K_2 smaller than 0.95. Considering the results above, the following practical procedure to predict δ_r is proposed.

 $\cdot \delta_r = R_1$ when $K_1/K_2 \ge 0.95$ as shown (a) in Figure 7. $\cdot \delta_r = R_2$ when $K_1/K_2 < 0.95$ as shown (b) in Figure 7.

Figure 8 (1) shows results simply predicted by R_1 and Figure 8 (2) shows those obtained by the procedure above. As can be found in the figure,

the prediction error is, as shown in Figure8 (2), significantly reduced after considering R_2 or the 3rd peak displacement and the proposed procedure can be an effective tool to predict the residual displacement δ_r .

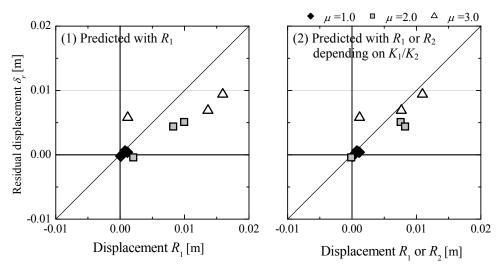


Figure 8: Relationship between δ_r , R_1 and R_2

3. PREDICTION OF RESIDUAL DISPLACEMENT USING EARTHQUAKE RESPONSE SPECTRA

In the previous section, a procedure to predict δ_r with R_1 , R_2 and K_1/K_2 (or P_1 , P_2 and P_3) are proposed. If the parameters above can be successfully predicted from the capacity spectrum method, the proposed procedure can be practically applicable in the structural design stage.

In the subsequent sections, a new approach to predict R_1 and R_2 from the capacity spectrum method is first proposed. It is then combined with the procedure described in section 2.4 and its applicability is discussed.

3.1 Prediction of peak responses with capacity spectrum method

A new approach to predict peak responses including those after the maximum using the capacity spectrum method is discussed. The procedure is shown in detail below. Note that the maximum response, i.e., the 1st peak response, is supposed to be found in the positive domain in this study.

[1]Firstly, the maximum displacement is predicted with the conventional capacity spectrum method in the positive domain using the structural capacity curve (i.e., backbone curve) and the demand spectrum (i.e., S_{A1} - S_{D1} curve) as shown point P₁* in Figure 9.

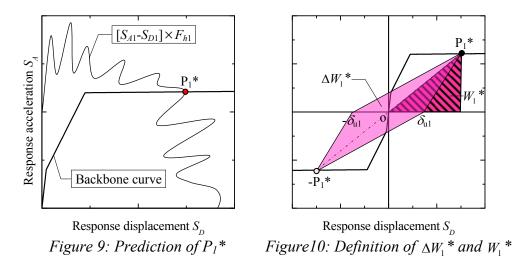
Setting *i* equal to 1 in Equations (3) and (4), the demand S_{A1} - S_{D1} curve is obtained by multiplying a reduction factor F_{h1} and the response spectrum with a 5% damping factor to consider the effect of hysteretic energy dissipation due to non-linear response. The equivalent damping factor

 h_{eq1} in Equation (3) is evaluated by Equation (4), and the definitions of dissipated energy ΔW_1^* and W_1^* are illustrated in Figure 10. The factor α_1 in Equation (4) is set 0.8 to predict the 1st peak response considering the notification No.1457 by the Japanese Ministry of Construction, which is generally applied in Japan and Midorikawa et al. (2003):

$$F_{h_i} = \frac{1.5}{1 + 10(h_{eqi} + 0.05)} \tag{3}$$

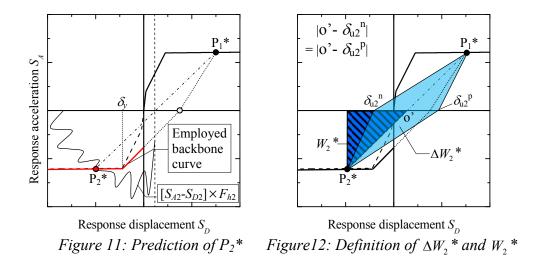
$$h_{eq_i} = \frac{1}{4\pi} \cdot \frac{\Delta W_i^*}{W_i^*} \times \alpha_i \tag{4}$$

where, ΔW_i^* is the hysteretic energy dissipation in one cycle, W_i^* is the equivalent potential energy, and α_i is a reduction factor to allow for non-stationary responses to predict P_i^* .

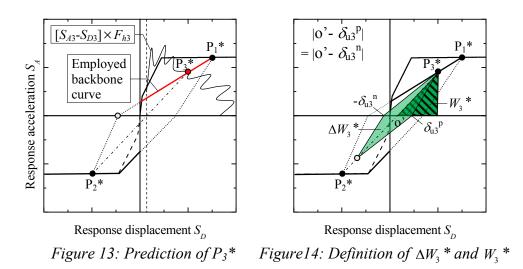


[2]Secondly, the 2nd peak is predicted in the negative domain using the concept analogous with the conventional capacity spectrum method as employed above.

The employed backbone curve to predict the 2nd peak P_2^* is shown in Figure 11, where the reloading curve in the negative displacement domain after P_1^* is used. Setting *i* equal to 2, the S_{A2} - S_{D2} curve is obtained from the spectrum of 2nd peak defined in section 2.1 and F_{h2} in Equations (3) and (4) where the factor α_2 is tentatively set 0.8 considering preliminary studies on the ratio of hysteretic energy dissipation to ΔW_2 during non-linear response analyses in chapter 2. The definitions of ΔW_2^* and W_2^* are shown in Figure 12 where the unloaded displacement in the negative domain δ_{u2}^n is assumed to follow the unloading rule of the Takeda model and the distance $|o' - \delta_{u2}^p|$ is equal to $|o' - \delta_{u2}^n|$ to represent a stationary response. During calculations, the 2nd peak P_2^* is initially assumed $-P_1^*$, and iterative calculations are performed until the predicted peak converges.



[3]The 3rd peak is evaluated in the positive domain in the analogous manner described earlier. The employed backbone curve to predict the 3rd peak P₃* is shown in Figure 13, where the reloading curve in the positive displacement domain after P₂* is used. Setting *i* equal to 3, the S_{A3} - S_{D3} curve is obtained from the spectrum of 3rd peak defined in section 2.1 and F_{h3} in Equations (3) and (4) where the factor α_3 is tentatively set 1.0 considering preliminary studies as is done for α_2 . The definitions of ΔW_3^* and W_3^* are shown in Figure 14 where the unloaded displacement in the positive domain δ_{u3}^{p} is assumed to follow the hysteric rule and the distance $|o' - \delta_{u3}^{p}|$ is equal to $|o' - \delta_{u3}^{n}|$. During calculations, the 3rd peak P₃* is initially assumed P₁*, and iterative calculations are performed until converged.



3.2 Residual displacement predicted through capacity spectrum concept

Peak responses P_1^* , P_2^* and P_3^* are obtained as shown in section 3.1 and then the residual displacement δ_r can be predicted by either R_1^* or R_2^* , which is the point where a line connecting P_N^* and P_{N+1}^* crosses the abscissa. Predicted results considering criteria shown in section 2.4 are compared with those obtained in the non-linear response analyses in Figure 15. As can be found in the figure, the predicted displacement using the capacity spectrum method compares well with those obtained from the nonlinear response analyses and the proposed method can successfully predict the residual displacement.

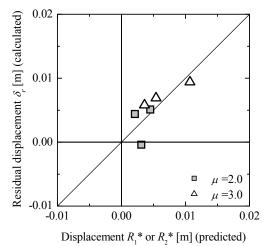


Figure 15: Relationship between δ_r , R_1^* , and R_2^*

4. CONCLUSION

- (1)A simplified method is proposed to predict the residual displacement where it is approximated by the point where the line connecting two displacement peaks in positive and negative domains of load-deflection curves crosses the abscissa. Its accuracy is much improved when the 3rd displacement peak is taken into account in addition to the 1st and 2nd displacement peaks.
- (2)The proposed method above is further extended and applied to the conventional capacity spectrum method to predict peak displacements. It is revealed that the method can successfully predict the residual displacements and enhance the conventional capacity spectrum method.

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